Understanding merge types in Teamwork Cloud

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The 3-way merge is the default method used to merge selected Teamwork Cloud projects; the ancestor version is calculated automatically depending on the selected ancestor calculation algorithm. Once the correct ancestor for the two selected project versions is calculated, the Merge dialog opens.



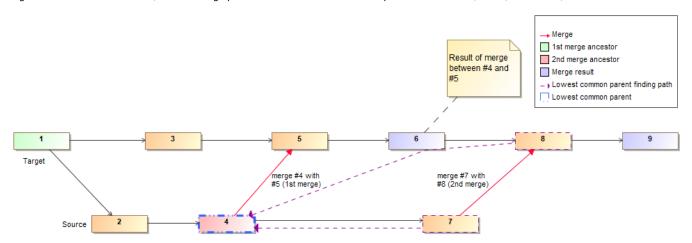
need to start the model merge from the Tools (Tools > Project Merge) menu to be able to change the ancestor selection (Lowest Common

Parent or Branch Point) for the model merge. By default, Lowest Common Parent is considered an ancestor of the selected project versions.

Lowest Common Parent (Default)

If Lowest Common Parent is selected, the lowest common version for both the Target and Source is considered an ancestor. The lowest common parent of two revisions of the Source and Target in a directed acyclic graph is the nearest revision that has both the Target and Source as descendants. The algorithm considers both the direct parent path and the merged path when traversing and searching for the lowest common parent. In other words, during the repeated merge, the Contributor from the Source that was participating in the last merge is considered to be the common ancestor.

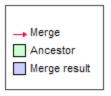
As shown in the image below, version #1 is considered to be a common parent during the first merge between versions #4 and #5. During the second merge between version #7 and #8, we traverse graphs back until we find the common parent for #7 and #8, which, in this case, is #4.

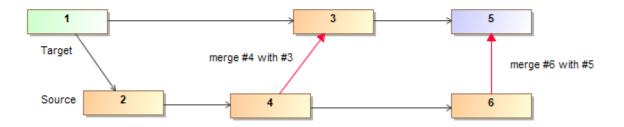


Visual representation of the model merge when Lowest Common Parent is considered an ancestor

Branch Point

If Branch Point is selected, the version from which the branches separate is considered an ancestor. As shown in the image below, version #1 is considered an ancestor in the first (version #4 is merged with version #3) and subsequent merges (version #6 is merged with version #5).





Visual representation of the model merge when Branch Point is considered an ancestor

Both ancestor calculation algorithms work in an identical way during the very first merge of the selected branches because the same ancestor is taken during the very first merge, no matter if the Branch Point or the Lowest Common Parent is specified. However, it is crucial to understand the importance of the ancestor selection during subsequent merges because the changes may differ greatly from those you expect to see (see examples below).

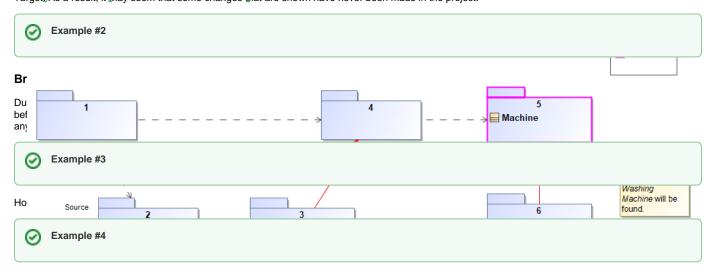
Repetitive merge

Lowest Common Parent

During the repeated merge, the Lowest Common Parent algorithm always chooses the latest merged Source version as the ancestor. Consequently, you do not need to review historical decisions made during previous merges.

Example #1 create a Class Machine in the Source branch and merge it with the Target (merge version #3 with version #4). Then continue your development process in the Source and rename Machine to Washing Machine. When you merge these two branches for the second time (merge version #6 with

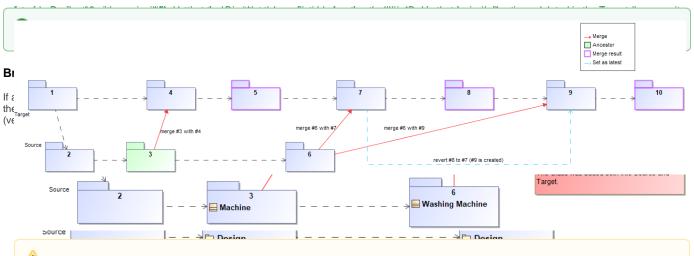
On the other hand the line was Someon Barant real wastern elagrithm may reuse sophusion since reinctions from the Source will appear as a deletion in the the inverted changes in the Target branch. For example, the created Class that was previously rejected in the Source will appear as a deletion in the Target pas is result in the Target pas is result in the Source will appear as a deletion in the Target pas is result in the Target pas is result in the Source will appear as a deletion in the Target pas is result in the Target pas



Set as Latest

Lowest Common Parent

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the default filter hides all the equivalent changes from Target and Source. Therefore, the creation of the Requirements package is hidden by default.